

Application of Model Order Reduction Techniques in LS-DYNA

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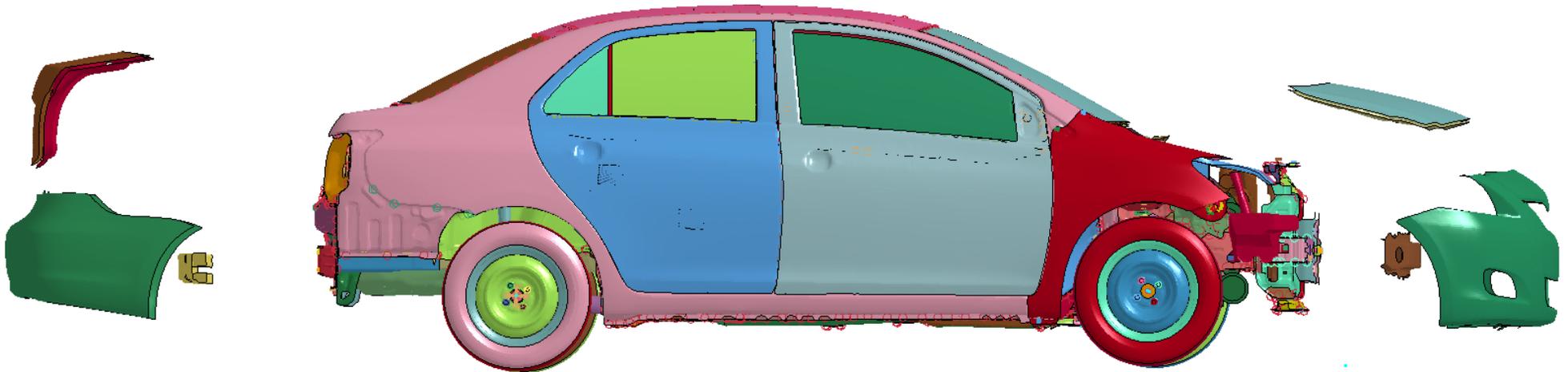
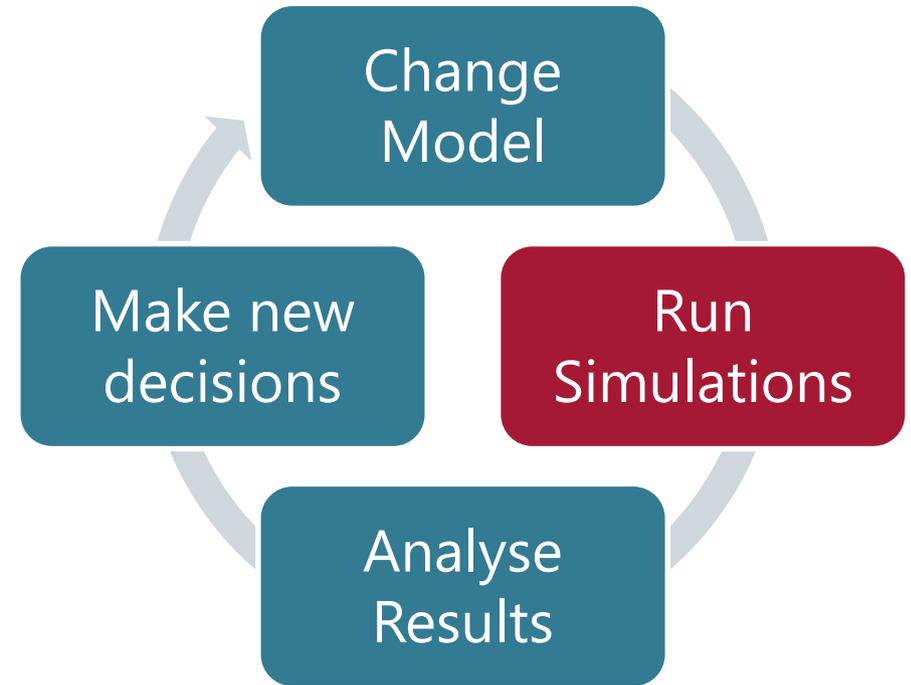
Daniel Weigert, AUDI AG

Outline

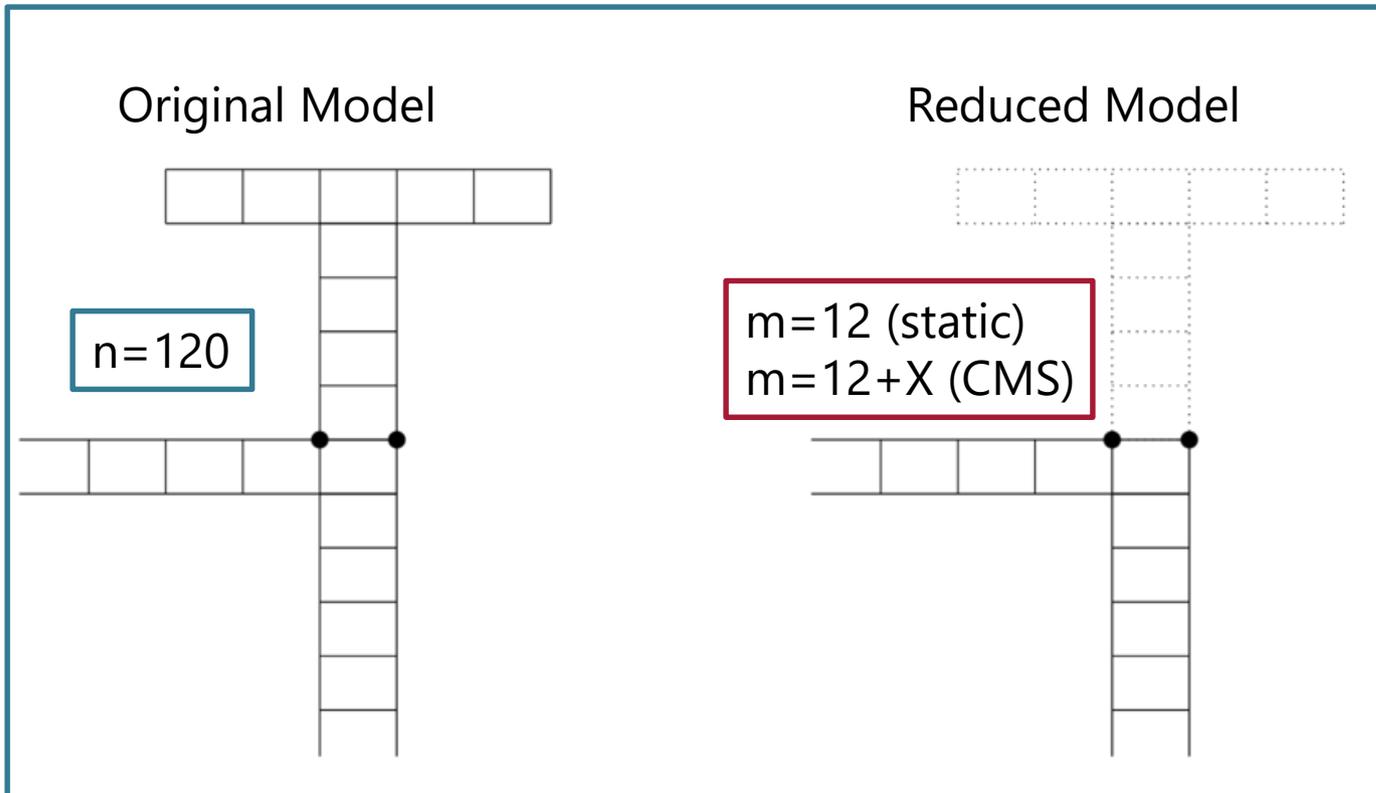
- Motivation
- Model Order Reduction
- Reduction Process in LS-DYNA
- Integration into simulation data management
- Example
 - Approximation Quality
 - Computing Time
- Conclusion
- Ongoing work

Motivation

- Large models in automotive crash simulation (~10Mio. elements)
- Many crash simulations during development iteration cycles
- Increased accuracy might not be necessary (different disciplines)
- Crash models already split in individual parts with clear interfaces
- Reduction of computing time by approximating specific areas
 - Model Order Reduction



Model order reduction



Static Condensation:

- No acceleration term
- Only accurate for low frequencies
- Simple to compute

Component Mode Synthesis (CMS):

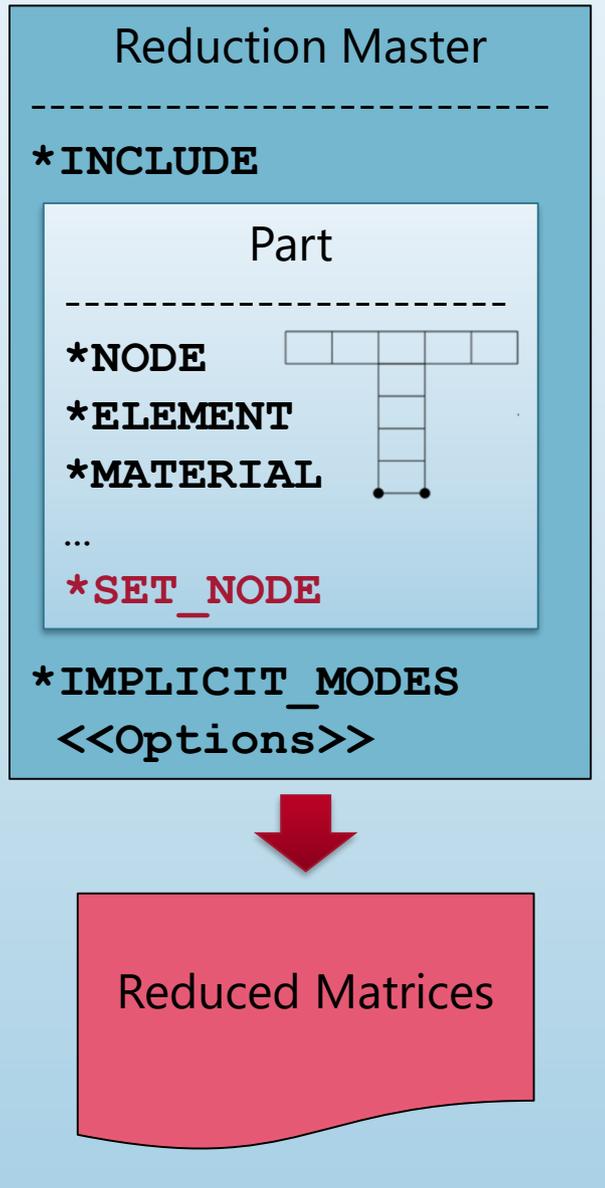
- Dynamic reduction
- Adds features of arbitrary eigenmodes to static condensation

Simplified Equation for Reduced Part

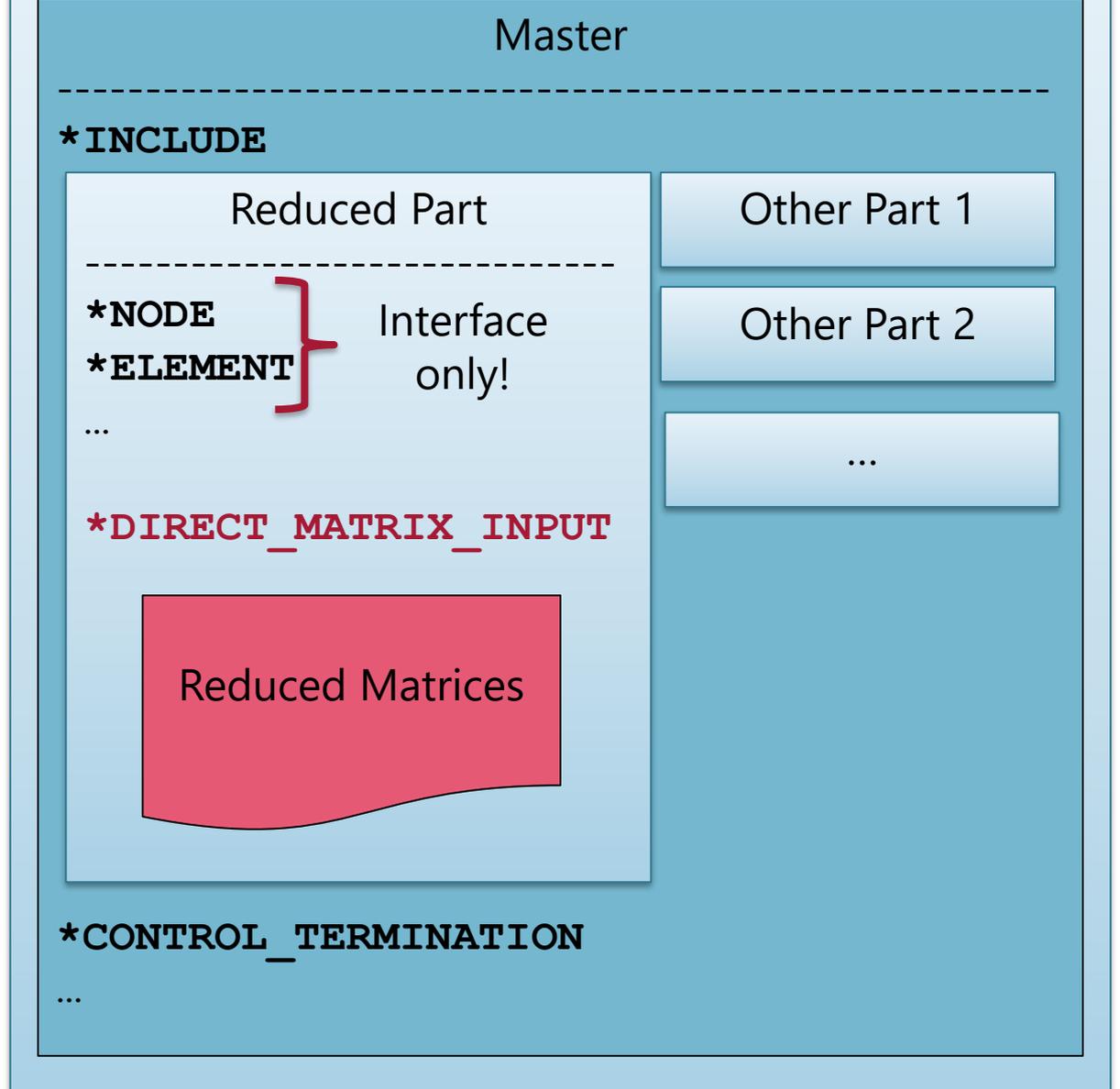
$$\begin{matrix} n \\ \left\{ \begin{matrix} \text{Blue Matrix} \\ \text{Dark Blue Vector} \end{matrix} \right\} + \begin{matrix} \text{Yellow Matrix} \\ \text{Red Vector} \end{matrix} = \text{Green Vector} \\ M \quad \ddot{x} \quad K \quad x \quad F \end{matrix} \quad \longrightarrow \quad \begin{matrix} m \\ \left\{ \begin{matrix} \text{Blue Matrix} \\ \text{Dark Blue Vector} \end{matrix} \right\} + \begin{matrix} \text{Yellow Matrix} \\ \text{Red Vector} \end{matrix} = \text{Green Vector} \\ M_r \quad \ddot{x}_r \quad K_r \quad x_r \quad F_r \end{matrix}$$

Reduction Process

Offline Step



Online Step



Integration into simulation data management

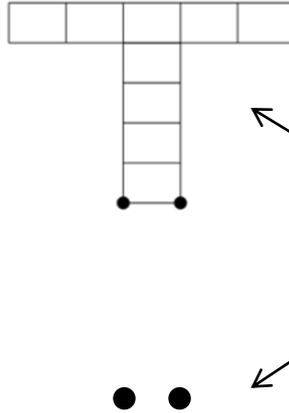
Step 1 – Original Model

SDM System

Part 1

1. Include

...



Step 2 – Adapt Original Part

SDM System

Part 1

1. Include with Master Nodes
2. Interface only Include

...

Step 3 – Automatic Reduction initiated by SDM System

SDM System

Part 1

1. Include with Master Nodes
2. Interface only Include

Reduction

...

Compute Node

Reduction

Reduced Matrices

Integration into simulation data management

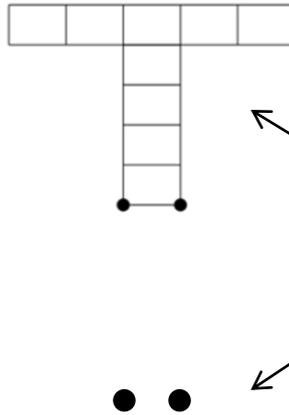
Step 1 – Original Model

SDM System

Part 1

1. Include

...



Step 2 – Adapt Original Part

SDM System

Part 1

1. Include with Master Nodes
2. Interface only Include

...

Step 3 – Automatic Reduction initiated by SDM System

SDM System

Part 1

1. Include with Master Nodes
2. Interface only Include

Reduction

For future simulations, original or reduced Part variant can be chosen

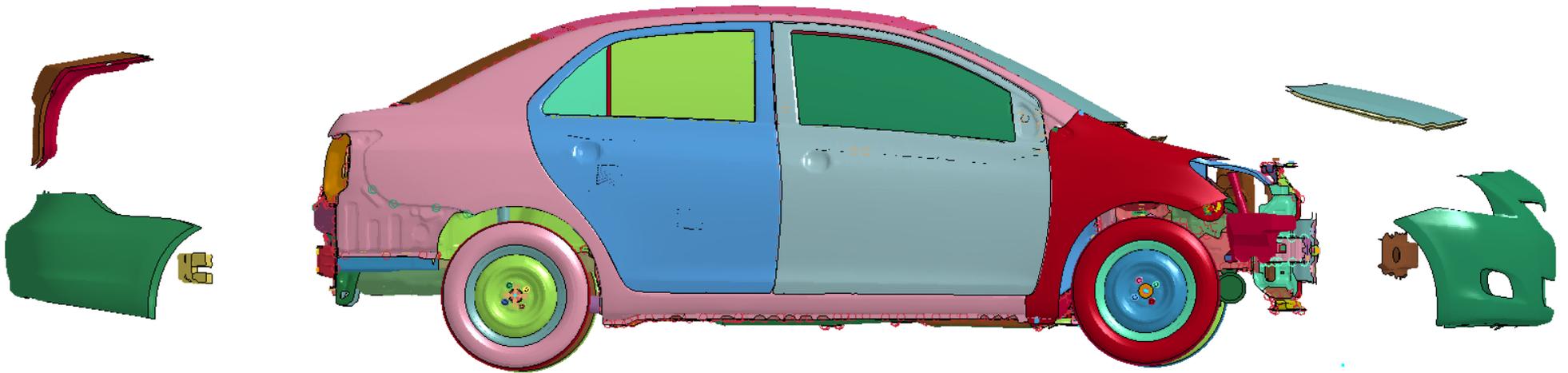
Compute Node

Once after every model change
Reduction

Reduced Matrices

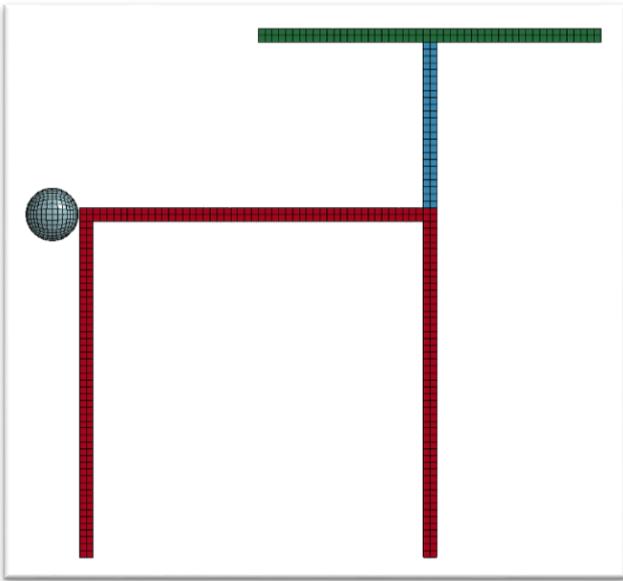
Integration into simulation data management

- Hold Original and Reduced model for several parts of the crash model
- Depending on the discipline (front-crash, rear-crash,...) choosing a combination of original and reduced variants
 - Possible because of modularity and interface modelling



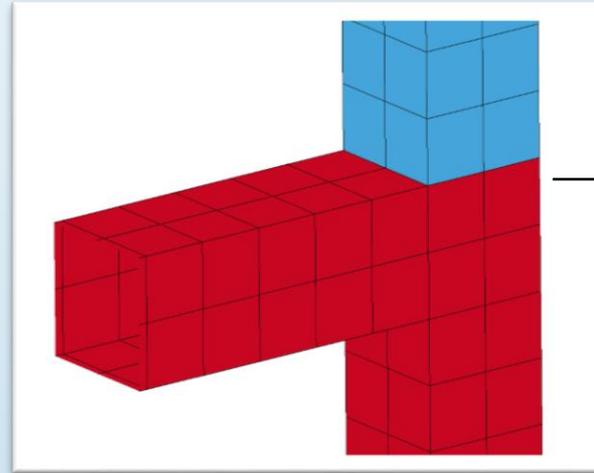
- Offline step already done automatically
- Reduced part can be used multiple times (in the same model or in different simulations)
 - More expensive Reduction method becomes viable

Examples: Model

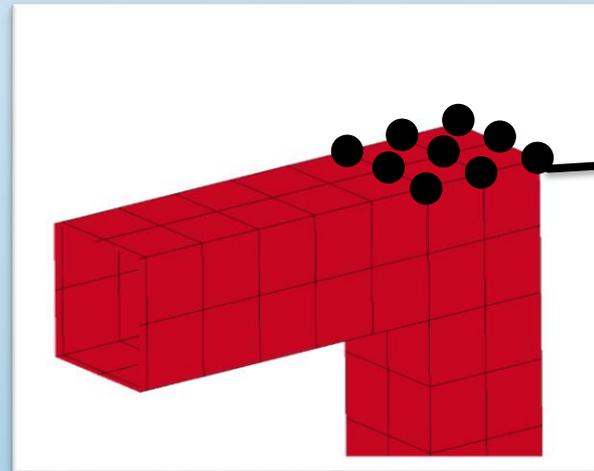


- Clamped Frame: 1212 nodes, 1224 shell elements
- „T”: 603 nodes, 608 shell elements
- Linear elastic material model
- Impactor sphere with initial velocity
- Reduction with static condensation and CMS with different numbers of modes

Detail: Interface Frame <-> „T”



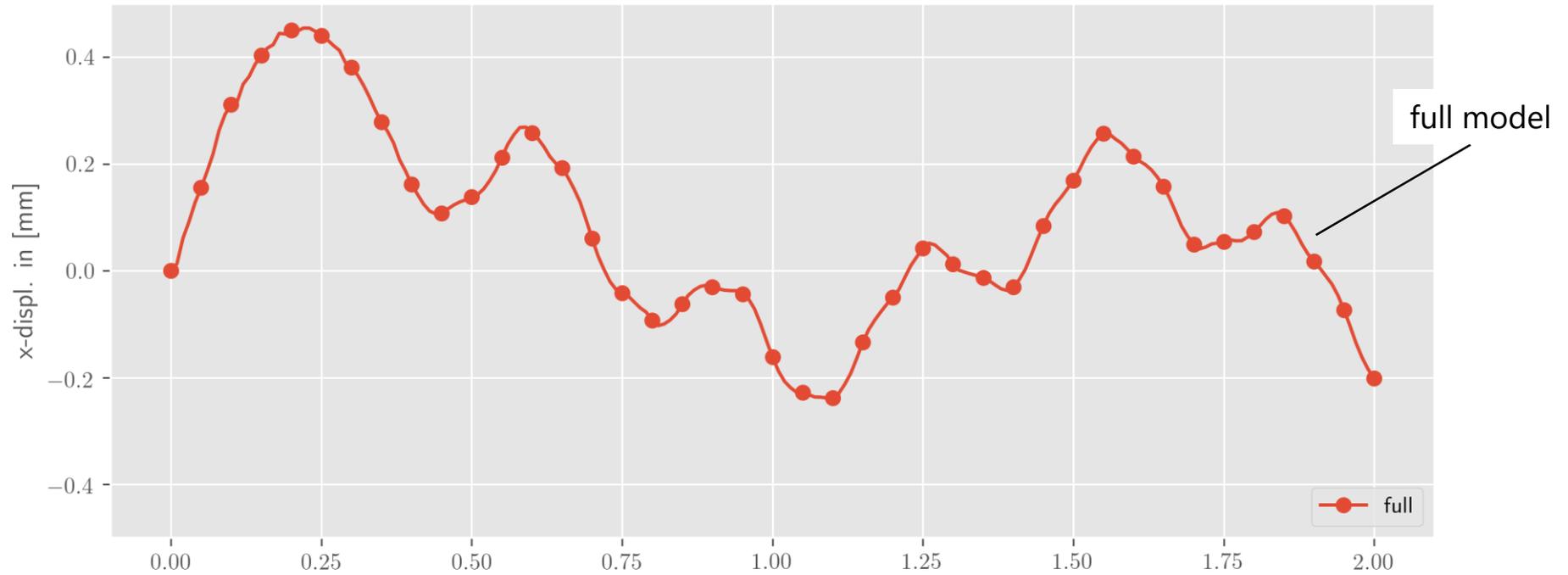
9 shared nodes
Between Parts



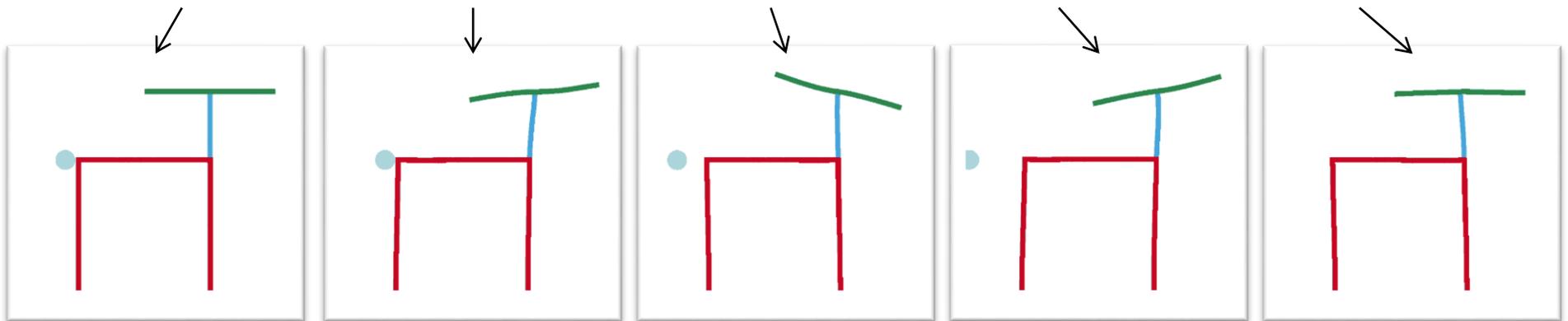
Connection
Nodes
=
Master Nodes
for Reduction

Examples: Approximation Quality

x-Displacement of impact point

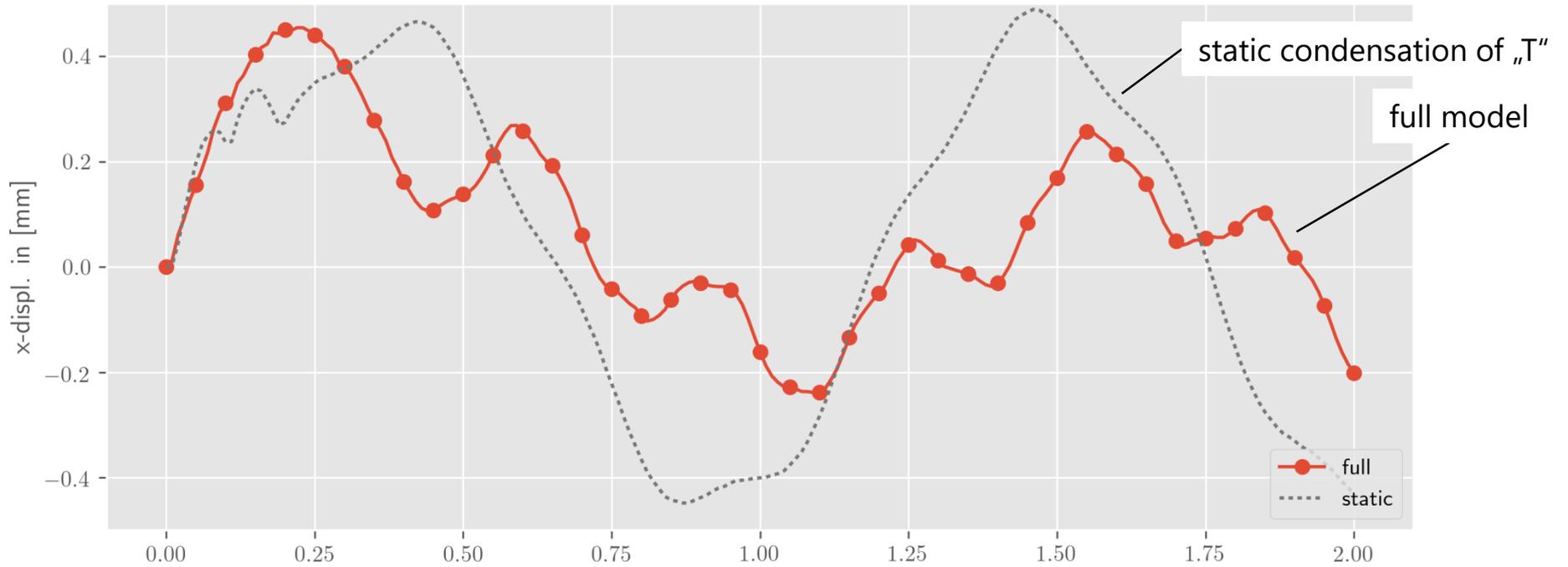


Stages:

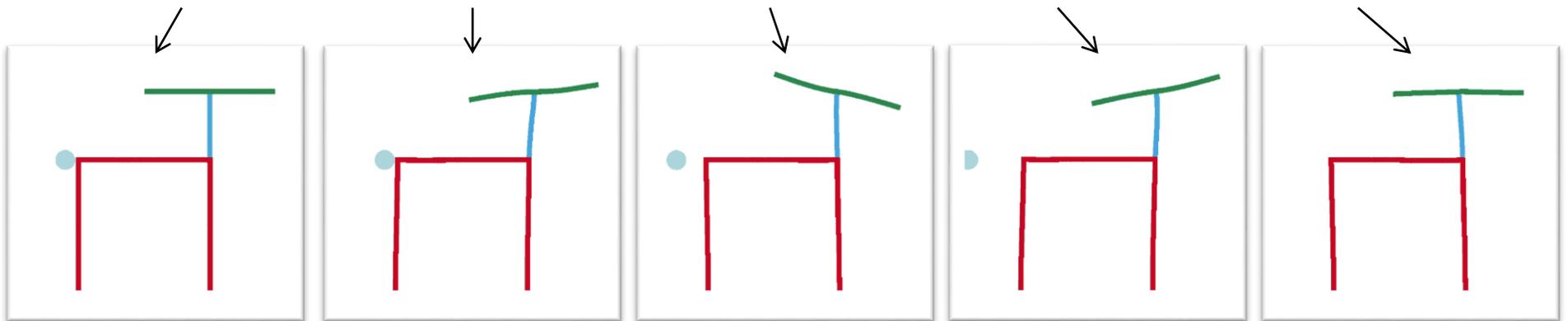


Examples: Approximation Quality

x-Displacement of impact point

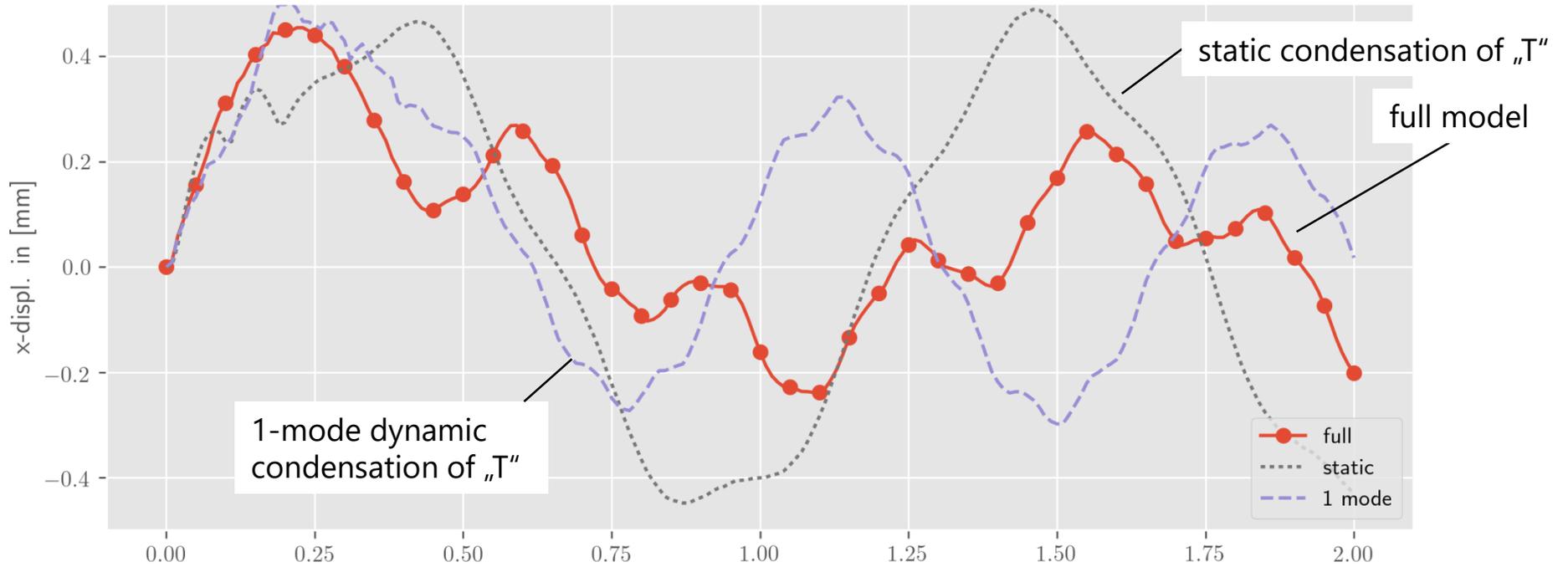


Stages:

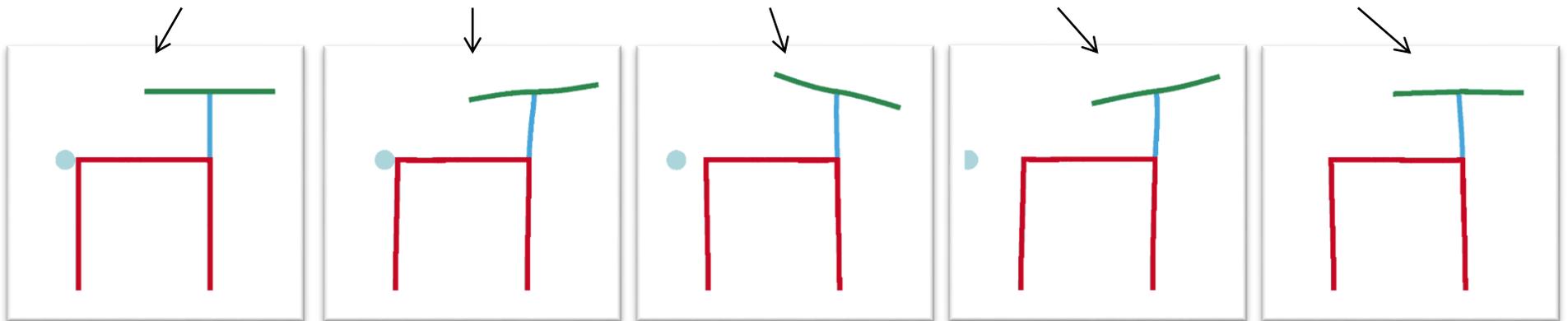


Examples: Approximation Quality

x-Displacement of impact point

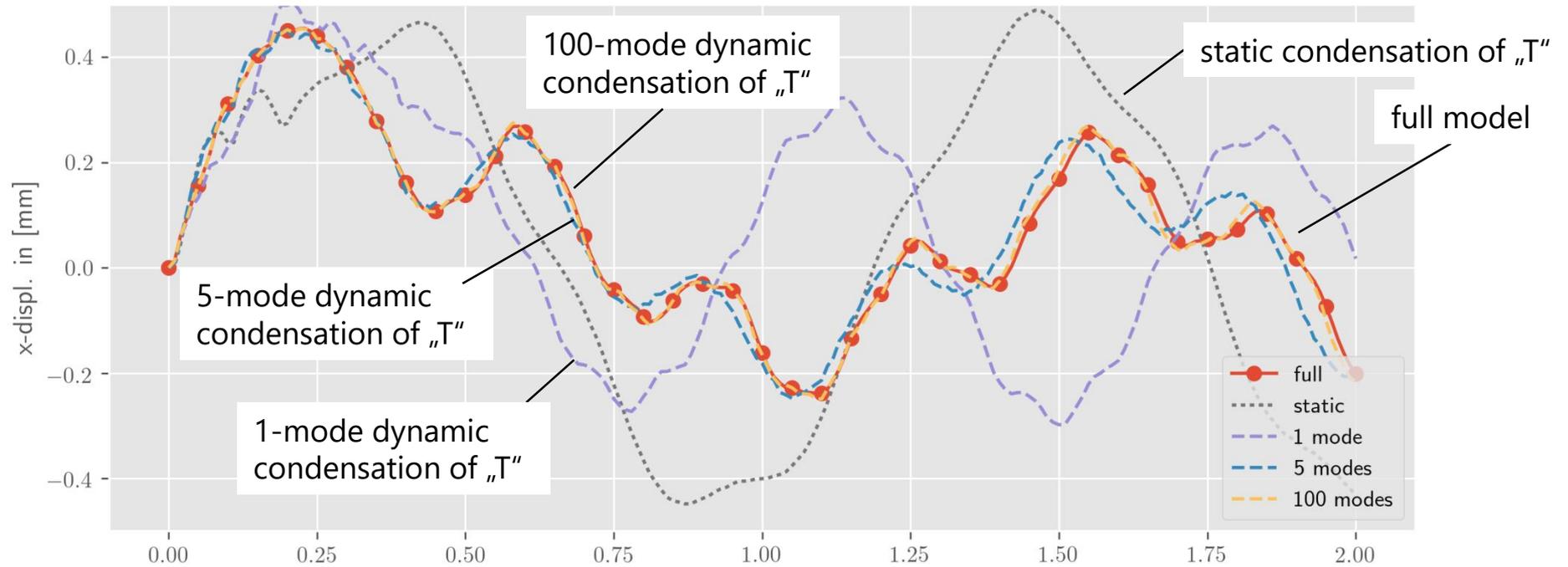


Stages:

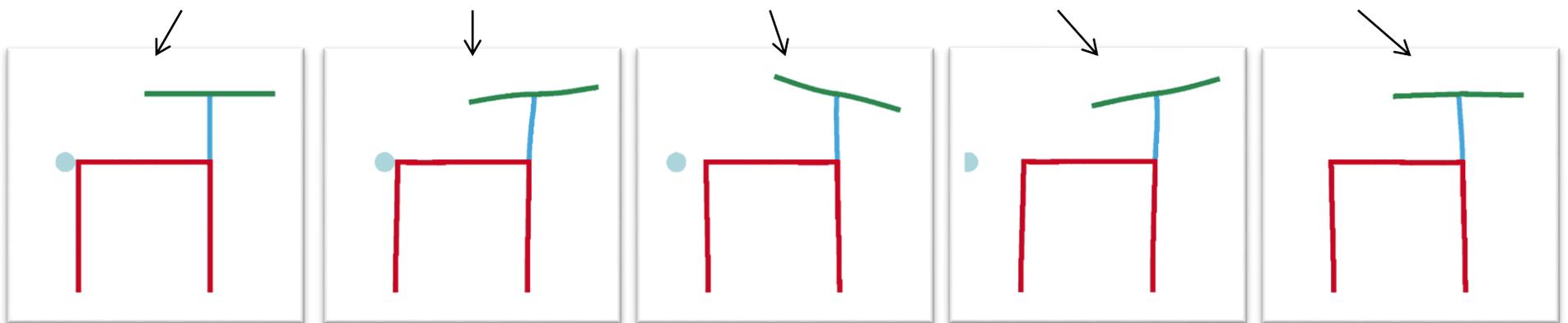


Examples: Approximation Quality

x-Displacement of impact point

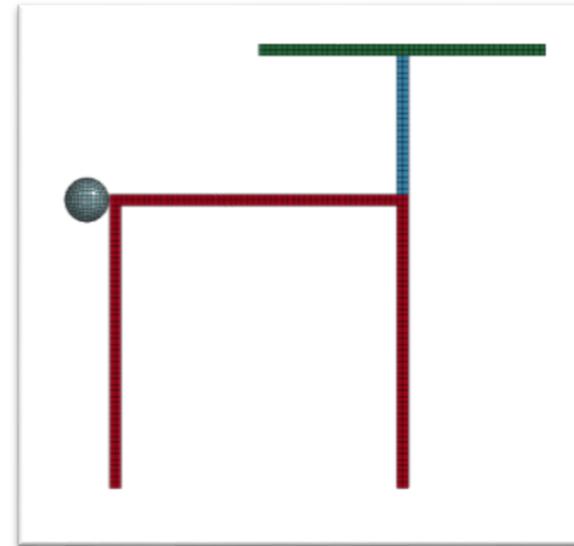
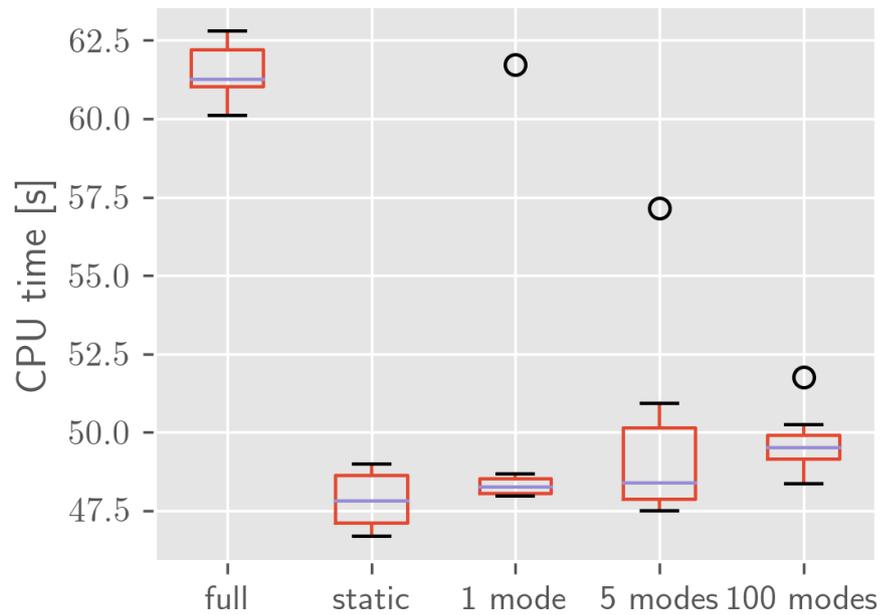


Stages:



Example: Computing Time

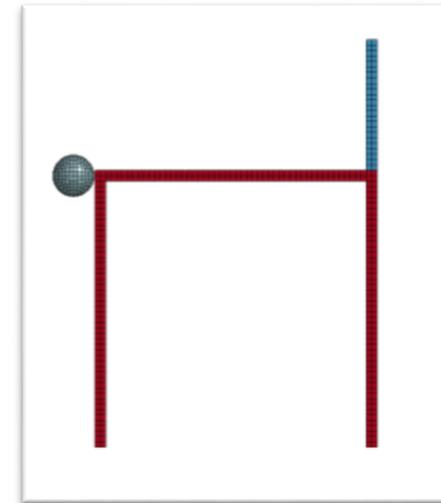
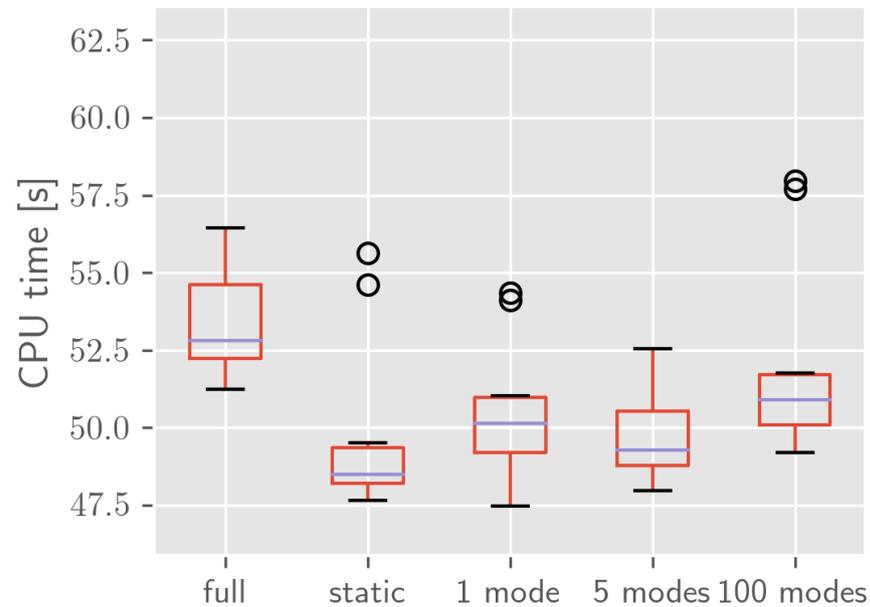
"T" substructure



T	DOF	CPU time [s]	DOF change [%]	CPU time change [%]
full	10890	61.26		
static	7326	47.80	-32.7	-21.9
1 mode	7327	48.25	-32.7	-21.2
5 modes	7331	48.39	-32.6	-21.0
100 modes	7426	49.50	-31.8	-19.1

Example: Computing Time

"I" substructure

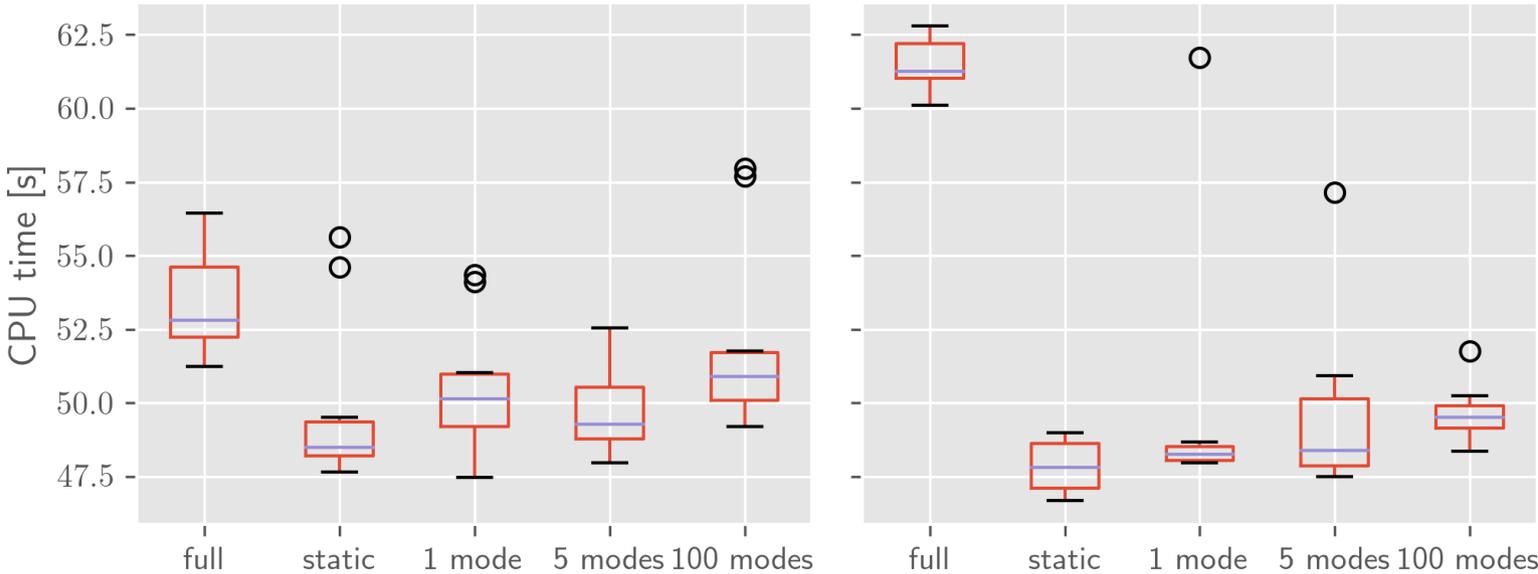
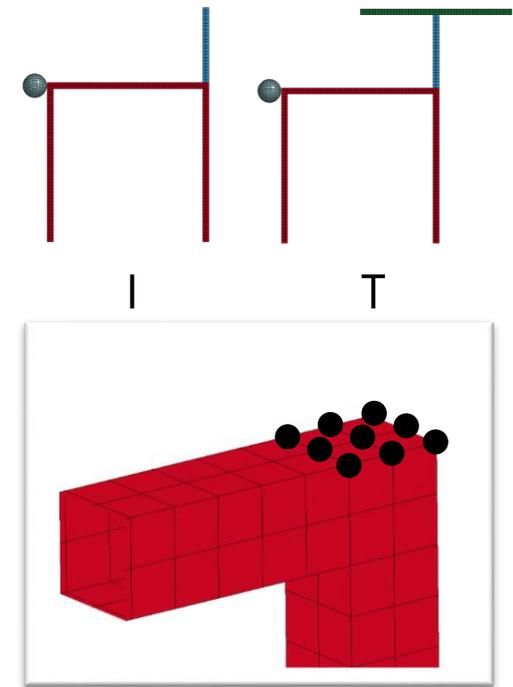


I	DOF	CPU time [s]	DOF change [%]	CPU time change [%]
full	8484	52.81		
static	7326	48.48	-13.6	-8.1
1 mode	7327	50.12	-13.6	-5.0
5 modes	7331	49.28	-13.5	-6.6
100 modes	7426	50.90	-12.4	-3.6

Examples: Computing Time

"I" substructure

"T" substructure



Reduction of Computing Time (with respect to reference sim.):

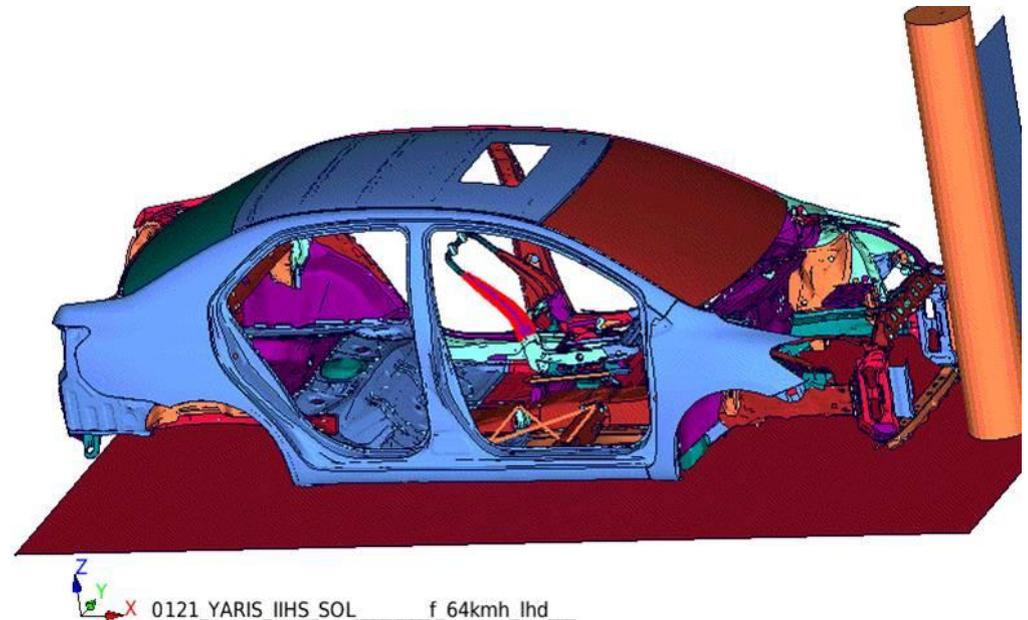
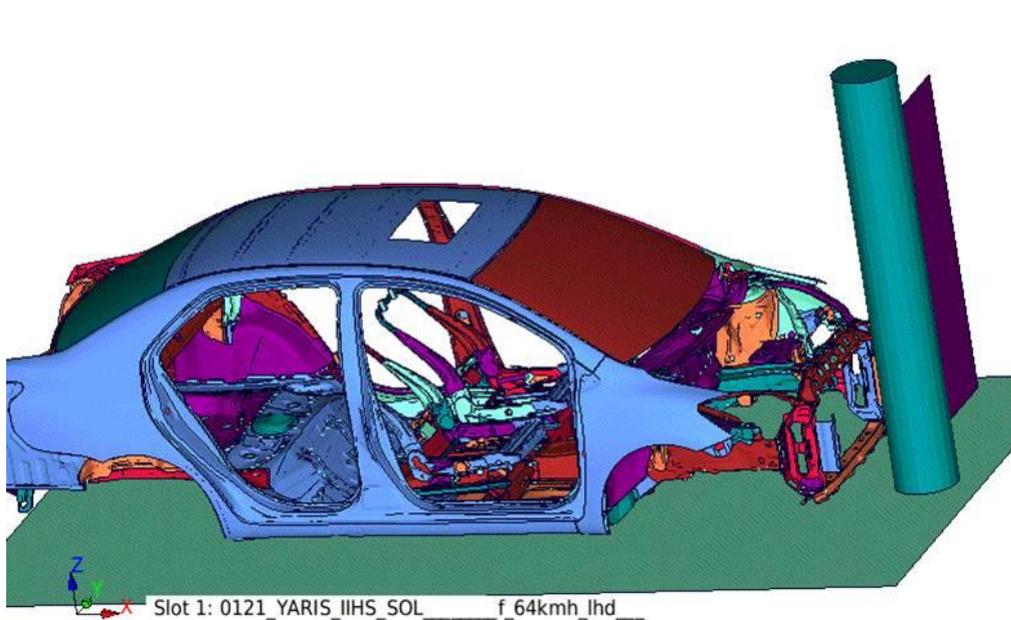
	T	(DOFs: -30%)	I	(DOFs: -13%)
static		-22.0%		-8.2%
1 mode		-21.1%		-5.1%
5 modes		-21.0%		-6.6%
100 modes		-19.2%		-3.6%

Conclusion

- General Process to use model order reduction with LS-DYNA:
 - Defining Master nodes; Reduction step; Import of reduced part as superelement
- Component mode synthesis (CMS) can be used to approximate the system response for the chosen academic example
- Approximation quality of CMS heavily depends on number of eigenmodes (also depends on the characteristics of the model)
- Significant computing time reduction can be achieved (depending on model size, with the examined models)
- Integration in existing workflows (e.g. SDM) is crucial to make MOR easily available
- By using a defined interface to connect parts, original parts and reduced parts can be interchanged

Ongoing Work

- Solve problems that occurred
- Outsource reduction step from LS-DYNA to external tools
 - Interface for system matrices is available (DMIG format)
- Improve the SDM integration (different reduction variants, scheduling of reduction run, caching,...)
- Using more complex models (more element types, failure, rigid bodies, damping,...)
 - Ultimately apply MOR to Toyota Yaris model

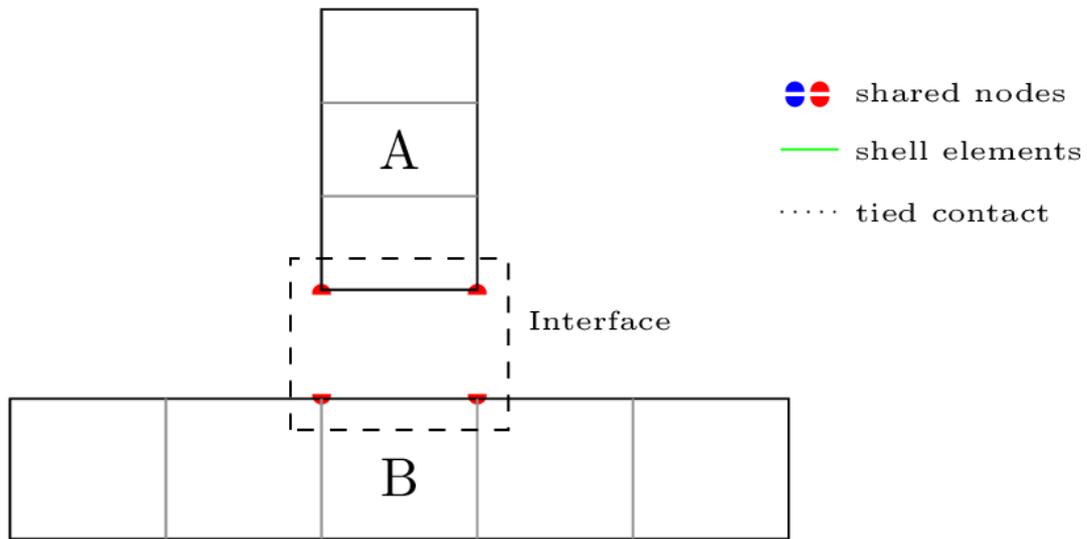


Thank you!

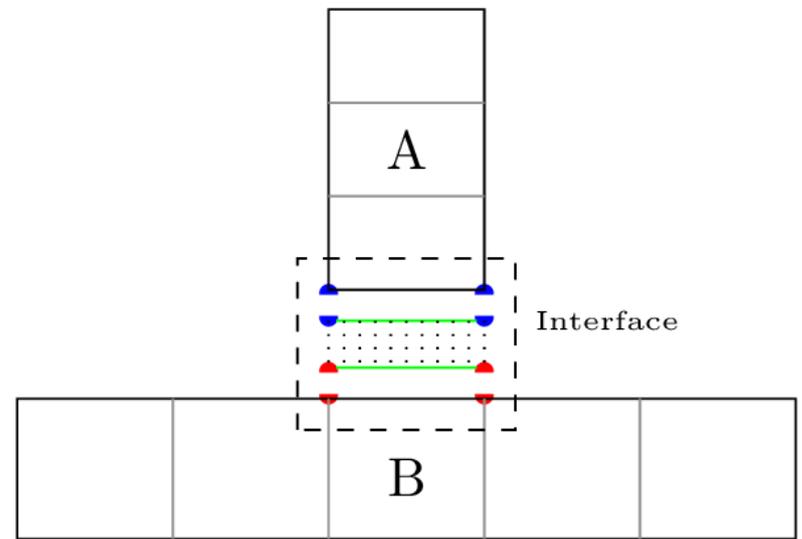
SCALE 

Interface

a) shared nodes



b) tied shell contact



Modulstrategie: Beispiel Yaris Heckklappe

